

MEc, Macro 2 Problem Set 1

1 Solving rational expectations models

(a) Suppose the variable y_t follows

$$y_t = \alpha_0 + \alpha_1 E_t y_{t+1} + u_t, \quad (1)$$

where u_t is of moving-average form, so

$$u_t = v_t + \theta v_{t-1}, \quad (2)$$

and where v_t is white noise.

Find a solution for y_t .

(b) Suppose the variable y_t follows

$$y_t = \alpha_0 + \alpha_1 E_t y_{t+1} + \alpha_2 y_{t-1} + u_t, \quad (3)$$

where u_t is a first-order auto-regressive disturbance, so

$$u_t = \rho u_{t-1} + \xi_t, \quad (4)$$

and where ξ_t is white noise.

Given the conjecture

$$y_t = \phi_0 + \phi_1 y_{t-1} + \phi_2 u_{t-1} + \phi_3 \xi_t, \quad (5)$$

characterize the solutions for $\phi_0, \phi_1, \phi_2, \phi_3$. What can we say about ϕ_1 ?

2 Solving an RBC model

In this problem you are asked to solve a real business cycle model with the method of undetermined coefficients.

A log-linearized version of the RBC model (assuming perfect foresight) is given by

$$c_t = \frac{Y}{C}z_t + \frac{K}{\beta C}k_{t-1} - \frac{K}{C}k_t, \quad (6)$$

$$r_t = [1 - \beta(1 - \delta)][z_t - (1 - \rho)k_{t-1}], \quad (7)$$

$$0 = \eta(c_t - c_{t+1}) + r_{t+1}, \quad (8)$$

$$z_t = \phi z_{t-1} + \varepsilon_t. \quad (9)$$

Equation (6) is the resource constraint, equation (7) is the return function, equation (8) is the consumption Euler equation, and equation (9) specifies the disturbance term z .

To solve for the dynamics with the method of undetermined coefficients we need a conjecture. A natural conjecture is to assume that the three endogenous variables (k_t, c_t, r_t) are a function of the exogenous variable z_t and lagged values of the state variable k_t :

$$k_t = v_{kk}k_{t-1} + v_{kz}z_t \quad (10)$$

$$r_t = v_{rk}k_{t-1} + v_{rz}z_t \quad (11)$$

$$c_t = v_{ck}k_{t-1} + v_{cz}z_t, \quad (12)$$

where the coefficients $v_{kk}, v_{kz}, v_{rk}, v_{rz}, v_{ck}, v_{cz}$ are to be determined. Note also that

$$E_t z_{t+1} = \phi z_t \quad (13)$$

- (a) What are the coefficients v_{rk} and v_{rz} ?
- (b) Show that the coefficient v_{ck} is equal to

$$v_{ck} = \frac{K}{\beta C} - \frac{K}{C}v_{kk}.$$

- (c) What is the coefficient v_{cz} ? (It is similar to v_{ck} .)
- (d) Show that

$$v_{kk} = \frac{v_{ck}}{v_{ck} - v_{rk}/\eta}.$$

(e) Show that

$$v_{kz} = \frac{v_{cz} - v_{cz}\phi + v_{rz}\phi/\eta}{v_{ck} - v_{rk}/\eta}.$$

(f) The coefficient v_{kk} relates the new value of the endogenous state variable k_t to its old value k_{t-1} , so it captures the essence of the dynamics of the system. Show that the solution for v_{kk} can be expressed as

$$0 = v_{kk}^2 - \gamma_1 v_{kk} + \gamma_2.$$

What are γ_1 and γ_2 ?

(g) Recall that the roots of the quadratic equation $ax^2 + bx + c = 0$ are

$$x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}.$$

In exercise (f), what are a , b , and c ? Can you say anything about which is the relevant root for our problem?